# Comparative Analysis of Fixed-Point Theorems: From Standard Metric to Generalized Extended b<sup>2</sup>-Metric Spaces with Contractions

#### Shruti Maheshwari

Department of Mathematics, Government Degree College Nanauta, Saharanpur shruti@gmail.com

Abstract: Z. Mustafa [8] introduced generalized metric space called b2-metric space. Kamran et al. [7], have dealt with an extended bmetric space. The aim of this paper is to establish a notion of a generalized extended b2 metric space which extends and generalizes metric space due to Z. Mustafa [8], Khan et al [10] and Kamran et al. [7]. Also we prove a fixed point theorem on a generalized extended b2 metric space.

Keywords: metric space, b metric space, 2 metric space, generalized 2 metric space, extended 2 metric space.

2020 AMS Subject Classification: 47H10, 54H25

#### 1. Introduction

The notion of a 2-metric space was introduced by Gahler, in [4]. Several fixed-point results were obtained in [1,2,3,4,5 6], as a generalization of the concept of a metric space. A 2-metric is not a continuous function of its variables, whereas an ordinary metric is. The basic philosophy is that since a 2-metric measures area, a contraction should send the space towards a configuration of zero area, which is to say a line.

Z. Mustafa introduced a new type of generalized metric space called b2-metric space, as a generalization of the 2-metric space, [8].

Recently, Kamran et al., have dealt with an extended b-metric space and obtained unique fixed-point results, [7].

**Definition 1.1. [4,9]** Let X be a non-empty set and d :X×X×X  $\rightarrow$  R<sub>+</sub> be a map satisfying the following properties

(i) d(x,y,z) = 0 if at least two of the three points are the same .

(ii) For x,  $y \in X$  such that  $x \neq y$  there exists a point  $z \in X$  such that  $d(x,y,z) \neq 0$ .

(iii) symmetry property: for x, y,  $z \in X$ ,

d(x,y,z) = d(x,z,y) = d(y,x,z) = d(y,x,z) = d(y,x,z) = d(y,z,x) = d(z,y,x).(iv) rectangle inequality:

 $d(x,y,z) \leq d(x,y,t) + d(y,z,t) +$ 

d(z,x,t)for x,y,z,t  $\in X$ . Then d is a 2-metric and (X, d) is a 2-metric space.

**Definition 1.2. [8]** Let X be a non-empty set and d :X×X×X  $\rightarrow$  R<sub>+</sub> be a map satisfying the following properties

(i) d(x,y,z) = 0 if at least two of the three points are the same. (ii) For x,y  $\in$  X such that x  $\neq$ y there exists a point z  $\in$ X such that  $d(x,y,z) \neq 0$ .

(iii) symmetry property: for x,y,z $\in$ X,

d(x,y,z) = d(x,z,y) = d(y,x,z) = d(y,z,x) =

d(z,x,y) = d(z,y,x).(iv) s-rectangle inequality: there exists  $s \ge 1$  such that  $d(z,y,z) \le 1 d(y,z,z) + d(y,z,z) + d(y,z,z)$ 

 $d(x,y,z){\leq}s[d(x,y,t)+d(y,z,t)+d(z,x,t)]$  for x,y,z,t  $\in$  X.

Then d is a b2-metric and (X, d) is a b2-metric space If s=1, the b2-metric reduces to the 2-metric.

**Definition 1.3.** [10] Let X be a non-empty set and d :X×X×X  $\rightarrow$  R<sub>+</sub> be a map satisfying the following properties:

(i) d(x,y,z) = 0 if at least two of the three points are the same. (ii) For  $x,y \in X$  such that  $x \neq y$  there exists a point  $z \in X$  such that  $d(x,y,z) \neq 0$ .

(iii) symmetry property: for x,y,z $\in$ X,

d(x,y,z) = d(x,z,y) = d(y,x,z) = d(y,z,x) = d(z,x,y) = d(z,y,x).

(iv) modified rectangle inequality: there exists  $\alpha$ ,  $\beta$ ,  $\gamma \ge 1$  such that

$$d(x,y,z) \le \alpha d(x,y,t) + \beta d(y,z,t)$$

+  $\gamma d(z,x,t)$ ] for x,y,z,t  $\in$  X.

Then d is a generalized b2-metric and (X,d) is a generalized b2- metric space.

If  $\alpha = \beta = \gamma = s$  then a generalized b2-metric is a b2-metric. If  $\alpha = \beta = \gamma = 1$  then the b2- metric is a 2-metric. The example that follows provides a motivation for the generalization of the concept of a b2-metric.

In recent times, Kamran et al. [19] introduced an expansion of b-metric space known as extended b-metric space.

**Definition 1.4.** [19] Consider a nonempty set S and a mapping  $\varphi : S \times S \rightarrow [1, +\infty)$ . A mapping  $d_{\varphi} : S \times S \rightarrow [0, +\infty)$  is known to be an extended b-metric space if it satisfies the succeeding assumptions:

 $\begin{array}{l} (d_{\phi}1) \ d_{\phi}(x,\,y) = 0 \ if \ x = y, \\ (d_{\phi} \ 2) \ d_{\phi}(x,\,y) = d_{\phi}(x,\,y), \\ (d_{\phi} \ 3) \ d_{\phi}(x,\,y) \leq \phi(x,\,y) \ \{ \ d_{\phi}(x,\,z) + d_{\phi}(z,\,y) \} \end{array}$ 

## Volume 7 Issue 6 2025 http://www.bryanhousepub.com

for every x, y, z  $\in$  S. (S,  $d_{\phi})$  is known as an extended b-metric space.

Inspired from Definition 1.3 and Definition 1.4 given above, here in this paper we introduce the concept of generalized extended b2-metric space and we prove a fixed point result in this space.

#### 2. Main Result

In this section, we introduce the following generalized extended b2 metric space and then prove a fixed point result on it.

**Definition 2.1** Let X be a non-empty set Let  $\rho$ ,  $\tau$ ,  $\sigma$ : X×X×X  $\rightarrow$  [1, + $\infty$ ) and d :X×X×X  $\rightarrow$  R<sub>+</sub> be a map satisfying the following properties:

(i) d(x,y,z) = 0 if at least two of the three points are the same. (ii) For x,y $\in$ X such that x  $\neq$ y there exists a point z  $\in$ X such that  $d(x,y,z) \neq 0$ .

(iii) symmetry property: for  $x,y,z \in X$ ,

d(x,y,z) = d(x,z,y) = d(y,x,z) = d(y,z,x) =

d(z,x,y) = d(z,y,x).(iv) modified rectangle inequality:

 $\begin{array}{rcl} d(x,y,z) &\leq & \rho(x,y,z) & d(x,y,t) &+ \\ \tau(x,y,z)d(y,z,t) + &\sigma(x,y,z)d(z,x,t)] & \\ & \text{for } x,y,z,t \in X. \end{array}$ 

If  $\rho(x,y,z) = \alpha$ ,  $\tau(x,y,z) = \beta$ ,  $\sigma(x,y,z) = \gamma$  then a generalized extended b2-metric is a generalized b2-metric  $\rho(x,y,z) =$  $\tau(x,y,z) = \sigma(x,y,z) =$ s then a generalized extended b2-metric is a b2-metric. If  $\rho(x,y,z) = \tau(x,y,z) = \sigma(x,y,z) = 1$  then a generalized extended b2-metric is a 2-metric.

**Definition 2.2.** Let  $\{x_n\}n \in N$  be a sequence in a generalized b2-metric space (X, d).

a) the sequence  $\{x_n\}n\in N$  is convergent to  $x\in X$  iff for all  $z\in X$  ,  $lim_{n\to\infty}d(x_n,x,z)=0.$ 

b) the sequence  $\{x_n\}n \in N$  is a Cauchy sequence in X iff for all  $z \in X$ ,  $\lim_{n,m\to\infty} d(x_n,x_m,z) = 0$ .

**Definition 2.3:** Let  $\varphi : \mathbb{R}_+ \to \mathbb{R}_+$  be a function satisfying

i)  $\varphi$  is continuous

ii)  $\varphi(t) < t$ 

iii)  $\sum_{1}^{n} \varphi^{i}(t) < \infty$ 

iv)  $\lim_{t \to \infty} \sum_{i=1}^{n} \varphi^{i}(t) \to 0 \text{ as } n \to \infty.$ 

**Theorem 2.5**: Let (X,d) be a complete generalized extended b2-metric space and T :  $X \rightarrow X$  be a self mapping

(1)  $d(Tx, Ty, z) \le \varphi(d(x, y, z))$  ( $\varphi$ - contraction)

for all  $x,y,z \in X$ . Then T has a fixed point in X. Also assume that max  $\{\rho(x,y,z), \tau(x,y,z) \sigma(x,y,z)\} < 1/k$  where  $k \in (0, 1)$ .

**Proof:** Let  $x_0 \in X$  and define a sequence  $\{x_n\}$   $n \in N$  in X by  $x_n=Tx_{n-1}$ , for all  $n \in N$ . We shall

show that the sequence  $\{x_n\} \ n \in N$  is a Cauchy sequence of real. Using (1), we get

 $d(x_n, x_{n+1}, z) = d(Tx_{n-1}, Tx_n, z) \le \varphi(d(x_{n-1}, x_n, z))$ which on repeating application implies that

 $\begin{aligned} \mathsf{d}(\mathsf{x}_n, \mathsf{x}_{n+1}, \mathsf{z}) &\leq \varphi^n(\mathsf{d}(\mathsf{x}_0, \mathsf{x}_1, \mathsf{z})) \\ \text{Let } \mathsf{n}, \mathsf{m} \in \mathsf{N} \text{ so that } \mathsf{n} < \mathsf{m}, \end{aligned}$ 

 $\begin{aligned} &d(x_n, x_m, z) \leq \rho(x_n, x_m, z) \ d(x_n, x_{n+1}, z) + \tau(x_n, x_m, z) d(x_n, x_m, x_{n+1}) + \sigma(x_n, x_m, z) d(x_{n+1}, x_m, z) \end{aligned}$ 

 $\leq \rho(x_n, x_m, z) \varphi^n(d(x_0, x_1, z)) + \tau(x_n, x_m, z) \varphi^n(d(x_0, x_1, x_m)) +$ 

$$\sigma(x_n, x_m, z)d(x_{n+1}, x_m, z) \leq \rho(x_n, x_m, z) \varphi^n(d(x_0, x_1, z)) + \tau(x_n, x_m, z) \varphi^n(d(x_0, x_1, x_m))$$

$$\begin{array}{c} \sigma(x_n, x_m, z) \left( \ \rho(x_{n+1}, x_m, z) \ \varphi^{n+1}(d(x_0, x_1, z)) + \\ \tau(x_{n+1}, x_m, z) \ \varphi^{n+1}(d(x_0, x_1, x_m)) + \sigma(x_{n+1}, x_m, z) d(x_{n+2}, x_m, z) \right) \end{array}$$

continuing we get d(x - x - z)

$$\sum_{i=0}^{m-n-1} \sigma(x_{n+i}, x_m, z) (\rho(x_{n+i+1}, x_m, z) \varphi^{n+i+1}(d(x_0, x_1, z)) + \sum_{i=0}^{m-n-1} \sigma(x_{n+i}, x_m, z) (\tau(x_{n+i+1}, x_m, z) \varphi^{n+i+1}(d(x_0, x_1, x_m)) + \sum_{i=0}^{m-n-1} \sigma(x_{n+i}, x_m, z) (\sigma(x_{n+i+1}, x_m, z) \varphi^{n+i+1}(d(x_0, x_1, z)))$$

$$\sum_{i=0}^{m-n-1} \frac{1}{k^2} \left( 2\varphi^{n+i+1} \left( d(x_0, x_1, z) \right) + \varphi^{n+i+1} \left( d(x_0, x_1, x_m) \right) \right)$$
  

$$\to 0 \text{ as } n \to \infty \qquad \text{by condition iv) of Definition 2.3.}$$

And so  $\lim_{n,m\to\infty} d(x_n, x_m, z) =0$  which state that  $\{x_n\}$  is a Cauchy sequence in complete generalized extended b2-metric space X so it is convergent in X i,e,  $\{x_n\}$  converges to some  $x \in X$ . Now we prove that x is a fixed point of T.  $d(x_n, Tx, z) = d(Tx_{n-1}, Tx, z) \le \varphi(d(x_{n-1}, x, z)) \le d(x_{n-1}, x, z)$ 

using condition i) of Definition 2.3

Which on letting  $n \to \infty$  gives d(x, Tx, z) = 0 so that Tx = x i.e. x is a fixed point of the mapping T.

For the uniqueness of x, let  $x \neq y \in X$  be such that Ty = y. Then

$$d(x, y, z) = d(Tx, Ty, z) \le \varphi(d(x, y, z)) <$$

d(x, y, z)

which is a contradiction. So x = y.

If we take  $\varphi(t) = kt$  where  $k \in (0, 1)$ , then  $\varphi$  -contraction is a Banach type contraction.

### References

- A. Aghajani, M. Abbas, J. Roshan, Common fixed point of generalized weak contractive mappings in partially ordered b-metric spaces, Math. Slovaca, 64 (2014), 941–960. https://doi.org/10.2478/s12175-014-0250-6.
- [2] S. Czerwik, Contraction mappings in b-metric spaces, Acta Math. Inform. Univ. Ostrav. 1 (1993), 5–11. http://dml.cz/dmlcz/120469.
- [3] S. Czerwik, Nonlinear set-valued contraction mappings in b-metric spaces, Atti Sem. Mat. Fis. Univ. Modena, 46 (1998), 263–276. https://cir.nii.ac.jp/crid/1571980075066433280.
- [4] S. Gahler, 2-metrische Raume und ihre topologische Struktur, Math. Nachr. 26 (1963), 115–148. https: //doi.org/10.1002/mana.19630260109.
- [5] M. Geraghty, On contractive mappings, Proc. Amer. Math. Soc. 40 (1993), 604–608.

## Volume 7 Issue 6 2025 http://www.bryanhousepub.com

- [6] T.L. Hicks, B.E. Rhoades, A Banach type fixed point theorem, Math. Japon. 24 (1979), 327–330. https: //cir.nii.ac.jp/crid/1572824499579575040.
- T. Kamran, M. Samreen, Q. UL Ain, A generalization of b-metric space and some fixed point theorems, Mathematics, 5 (2017), 19. https://doi.org/10.3390/math5020019.
- [8] Z. Mustafa, V. Parvaneh, J.R. Roshan, et al. b2-Metric spaces and some fixed point theorems, Fixed Point Theory Appl. 2014 (2014), 144. https://doi.org/10.1186/1687-1812-2014-144.
- [9] P. Singh, V. Singh, S. Singh, Some fixed points results using (ψ,φ)-generalized weakly contractive map in a generalized 2-metric space, Adv. Fixed Point Theory, 13 (2023), 21. https://doi.org/10.28919/afpt/8218.
- [10] S.H. Khan, P. Singh, S. Singh, et al. Fixed point results in generalized bi-2-metric spaces using  $\theta$ -type contractions, Contemp. Math. 5 (2024), 1257–1272
- [11] O. Ege and I. Karaca, Common fixed point results on complex valued Gb-metric spaces, Thai J. Math. 16, 3, 775-787, 2018.
- [12] O. Ege, C. Park and A. H. Ansari, A different approach to complex valued Gb-metric spaces, Adv. Difference Equ. 2020, 152, 1-13, 2020.
- [13] A. Gholidahneh, S. Sedghi, O. Ege, Z. D. Mitrovic and M. de la Sen, The Meir-Keeler type contractions in extended modular b-metric spaces with an application, AIMS Math. 6, 2, 1781-1799, 2021.
- [14] V. Gupta, O. Ege, R. Saini and M. de la Sen, Various fixed point results in complete Gb-metric spaces, Dynam. Systems Appl. 30, 2, 277-293, 2021.
- [15] A. Hassen, R. Dusan, A. Aghajani, T. Dosenovic, M. Salmi, M. Nooraniand and H. Qawaqneh, On fixed point results in Gb-metric spaces, Mathematics, 2019, 7, 617, doi:10.3390/math7070617.
- [16] M. Iqbal, A. Batool, O. Ege and M. de la Sen, Fixed point of almost contraction in b-metric spaces, J. Math. 3218134, 1-6, 2020.
- [17] M. Iqbal, A. Batool, O. Ege and M. de la Sen, Fixed point of generalized weak contraction in b-metric spaces, J. Funct. Spaces 2021, 2042162, 1-8, 2021.
- [18] T. Kamran, M. Samreen and O.U Ain, A generalization of b-metric space and some fixed point theorems, Mathematics 5, 2, 2017.